

Education

- 2019 – Now **Ph.D. in Computer Science at Stanford University**, Stanford, CA.
GPA 4.01
 - Co-advised by [Percy Liang](#) and [Dorsa Sadigh](#)
 - Supported by the [Open Philanthropy AI Fellowship](#) (5+ years of support)
 - Focus areas: *human-robot interaction, natural language processing, robotics*
- 2015 – 2018 **Sc.B in Computer Science. A.B. in Literary Arts at Brown University**, Providence, RI.
GPA 3.95
 - Graduated [Magna Cum Laude with Honors in Computer Science](#)
 - Thesis: Grounding natural language to goals for abstraction, generalization, and interpretability
 - Co-advised by [Eugene Charniak](#) and [Stefanie Tellex](#)
- 2014 – 2015 **Electrical Engineering & Computer Science, UC Berkeley**, Berkeley, CA.
GPA 3.92
 - Awarded the [Regents and Chancellor's Scholarship](#) (top 2% of incoming class)
 - Transferred to Brown after first year to pursue interdisciplinary education in CS + Literature

Research Experience

- 2019 – Now **Stanford University, Stanford, CA.**
Ph.D. Student co-advised by Percy Liang and Dorsa Sadigh
Conducting research in shared autonomy and language for robotic manipulation, self-supervised learning, with additional interests in multi-modality, language grounding, and interaction.
- 2021 – 2022 **Hugging Face, Remote – Palo Alto, CA.**
Research Intern in Multimodality and Scaling
Affiliated with the core Science team, as well as the open-source engineering team.
Conducted research in large-scale multimodal (text, vision, video, audio) modeling, with a goal of learning powerful contextual representations.
- 2018 – 2019 **Facebook AI Research, New York, NY.**
AI Resident; Advised by Rob Fergus, Douwe Kiela, Jason Weston, and Arthur Szlam
Conducted research at the intersection of deep reinforcement learning and natural language processing; additional work in text-based games.
- 2017 – 2018 **Bloomberg LP – CTO Research Group, New York, NY.**
Research Intern (Summer '17, '18, Part-Time '17-'18); Advised by Gideon Mann and David Rosenberg
Conducted research in automated bug detection (“fuzzing”) using machine learning, active learning.
- 2016 – 2018 **Human to Robots (H2R) Lab – Brown University, Providence, RI.**
Undergraduate Research Assistant; Advised by Stefanie Tellex.
Conducted research in human-robot interaction: instruction following for mobile manipulation.
- 2016 – 2018 **Brown Lab for Linguistic Information Processing (BLLIP), Providence, RI.**
Undergraduate Research Assistant; Advised by Eugene Charniak.
Research in computational social science, semantic parsing, and question-answering.

Honors and Awards

- 2022 Best Paper Finalist for “What Makes Representation Learning from Videos Hard for Control?” at the 2nd Workshop on Scaling Robot Learning at RSS 2022.
- 2022 Highlighted Reviewer at ICLR 2022.
- 2021 Outstanding Reviewer Award at EMNLP.
- 2021 Outstanding Paper award at ACL-IJCNLP for “Mind Your Outliers! Investigating the Negative Impact of Outliers on Active Learning for Visual Question Answering.” Awarded to the top 5 (0.2%) out of 3000+ submissions.

- 2021 Outstanding Reviewer Award at ACL-IJCNLP.
- 2019 Open Philanthropy Project AI Fellowship, offering full funding for 5+ years of the PhD, and access to broader network of fellows and affiliated research scientists.
- 2018 Selected for the inaugural Facebook AI Residency, 1/11 out of 2000+ applications.
- 2018 University Distinguished Thesis Nominee, Brown Computer Science. Sole CS-department nominee for University-wide undergraduate thesis prize.
- 2018 Honorable Mention – Computing Research Association (CRA) Outstanding Undergraduate Researcher Prize. One of 45 student recognized in nationwide competition.
- 2018 Senior Prize, Brown University Computer Science Department. Recognized for outstanding record in research, teaching, and service.
- 2017 Best Paper Award at RoboNLP Workshop @ ACL 2017 for “A Tale of Two DRAGGNs: Interpreting Action and Goal-Oriented Instructions.”
- 2014 Regents and Chancellor’s Scholarship – UC Berkeley. One of 200 incoming undergraduates recognized with the scholarship, as determined by the Academic Senate.

Peer-Reviewed Academic Publications

- CoRL 2022 **Eliciting Compatible Demonstrations for Multi-Human Imitation Learning.**
Kanishk Gandhi, **Siddharth Karamcheti**, Madeline Liao, Dorsa Sadigh
Conference on Robot Learning (CoRL) 2022
- SRL 2022 **What Makes Representation Learning from Videos Hard for Control?.**
Tony Z. Zhao, **Siddharth Karamcheti**, Thomas Kollar, Chelsea Finn, Percy Liang
2nd Workshop on Scaling Robot Learning (SRL) @ RSS, 2022
Best Paper Finalist
- NL-Sup 2022 **Shared Autonomy for Robotic Manipulation with Language Corrections.**
Siddharth Karamcheti, Raj Palleeti, Yuchen Cui, Percy Liang, Dorsa Sadigh
Workshop on Learning with Natural Language Supervision (NL-Sup) @ ACL, 2022
- NeurIPS 2021 **ELLA: Exploration through Learned Language Abstraction.**
Suvir Mirchandani, **Siddharth Karamcheti**, Dorsa Sadigh
Advances in Neural Information Processing Systems (NeurIPS), 2021
- CoRL 2021 **LILA: Language-Informed Latent Actions.**
Siddharth Karamcheti*, Megha Srivastava*, Percy Liang, Dorsa Sadigh
Conference on Robot Learning (CoRL), 2021
- ACL 2021 **Mind Your Outliers! Investigating the Negative Impact of Outliers on Active Learning for Visual Question Answering.**
Siddharth Karamcheti, Ranjay Krishna, Li Fei-Fei, Christopher D. Manning
Annual Meeting of the Association of Computational Linguistics (ACL-IJCNLP), 2021
Outstanding Paper Award (top 5 / 3000+ submissions) | Main Stage Presentation
- ICML 2021 **Targeted Data Acquisition for Evolving Negotiation Agents.**
Minae Kwon, **Siddharth Karamcheti**, Mariano-Florentino Cuéllar, Dorsa Sadigh
International Conference on Machine Learning (ICML), 2021
- L4DC 2021 **Learning Visually Guided Latent Actions for Assistive Teleoperation.**
Siddharth Karamcheti, Albert J. Zhai, Dylan P. Losey, Dorsa Sadigh
Learning for Dynamics and Control (L4DC), 2021
- IntEx-SemPar 2020 **Learning Adaptive Language Interfaces through Decomposition.**
Siddharth Karamcheti, Dorsa Sadigh, Percy Liang
Workshop for Interactive and Executable Semantic Parsing (IntEx-SemPar) @ EMNLP, 2020

- AAAI 2020 **Generating Interactive Worlds with Text.**
Angela Fan*, Jack Urbanek*, Pratik Ringshia, Emily Dinan, Emma Qian, **Siddharth Karamcheti**, Shrimai Prabhunoye, Douwe Kiela, Tim Rocktäshel, Arthur Szlam, Jason Weston
Association for the Advancement of Artificial Intelligence (AAAI), 2020
- EMNLP 2019 **Finding Generalizable Evidence by Learning to Convince Q&A Models.**
Ethan Perez, **Siddharth Karamcheti**, Rob Fergus, Jason Weston, Douwe Kiela, Kyunghyun Cho
Empirical Methods in Natural Language Processing (EMNLP), 2019
- Learning to Speak and Act in a Fantasy Text Adventure Game.**
Jack Urbanek, Angela Fan, **Siddharth Karamcheti**, Saachi Jain, Samuel Humeau, Emily Dinan, Tim Rocktäshel, Douwe Kiela, Arthur Szlam, Jason Weston
Empirical Methods in Natural Language Processing (EMNLP), 2019
- ML4SE 2019 **Improving Grey-Box Fuzzing by Modeling Program Control Flow.**
Siddharth Karamcheti, Gideon Mann, David Rosenberg
Workshop on Machine Learning for Software Engineering (ML4SE), 2019
- AuRO 2019 **Grounding Natural Language Instructions to Semantic Goal Representations for Abstraction and Generalization.**
Dilip Arumugam*, **Siddharth Karamcheti***, Nakul Gopalan, Edward C. Williams, Mina Rhee, Lawson L.S. Wong, Stefanie Tellex
Journal – Autonomous Robots (AuRO), 2019
- AISEC 2018 **Adaptive Grey-Box Fuzz Testing with Thompson Sampling.**
Siddharth Karamcheti, Gideon Mann, David Rosenberg
ACM Workshop on Artificial Intelligence and Security (AISEC), 2018
[Oral Presentation](#)
- RoboNLP 2017 **A Tale of Two DRAGNs: Interpreting Action and Goal-Oriented Instructions.**
Siddharth Karamcheti, Edward C. Williams, Dilip Arumugam, Mina Rhee, Nakul Gopalan, Lawson L.S. Wong, Stefanie Tellex
Workshop in Language Grounding for Robotics (RoboNLP) @ ACL, 2017
[Best Paper Award](#) | [Oral Presentation](#)
- RSS 2017 **Accurately and Efficiently Interpreting Instructions of Varying Granularities.**
Dilip Arumugam*, **Siddharth Karamcheti***, Nakul Gopalan, Lawson L.S. Wong, Stefanie Tellex
Robotics: Science and Systems (RSS), 2017

Manuscripts, Blog Posts & Non-Archival Publications

- Annotated S4 **The Annotated S4 – Structured State Space Models for Sequence Modeling.**
Sasha Rush and **Siddharth Karamcheti** – *ICLR Blog Track, 2022*
A literate implementation and associated blog post for the Structured State Spaces for Sequence Modeling (S4) architecture, with analysis of long-range generalization capabilities.
[Blog](#) || [Library](#): <https://github.com/srush/annotated-s4/> || [ICLR Blog Reviews](#)
- Mistral **Mistral: A Journey towards Reproducible Language Model Training.**
Siddharth Karamcheti* and Laurel Orr*
Codebase & associated writeup detailing our journey in scaling large-scale language model pre-training as part of the development team for the Center for Research on Foundation Models.
[Blog](#) || [Code & Checkpoints](#): <https://github.com/stanford-crfm/mistral>
- Foundation Models **On the Opportunities & Risks of Foundation Models.**
Center for Research on Foundation Models, led by Percy Liang. Authored the following sections:
 - o *Robotics*: **Siddharth Karamcheti** (lead author), Annie Chen, Suvir Mirchandani, Suraj Nair, Krishnan Srinivasan, Kyle Hsu, Jeannette Bohg, Dorsa Sadigh, Chelsea Finn
 - o *Interaction*: Joon Sung Park, Chris Donahue, Mina Lee, **Siddharth Karamcheti**, Dorsa Sadigh, Michael Bernstein
- Undergraduate Thesis **Grounding Language to Goals for Abstraction, Generalization and Interpretability.**
Siddharth Karamcheti – Submitted for fulfillment of Sc. B. Honors in Computer Science
[Nominated for University-level honors \(sole CS Department nominee\)](#)

Engineering Experience

- 2016 **Wealthfront Inc., Redwood City, CA.**
Software Engineering Intern
Backend software intern primarily working on data workflows, risk services.
- 2015 **WriteLab Inc., Berkeley, CA.**
Natural Language Processing Intern
NLP engineering intern, built systems for topic and entity tracking across large-scale documents (essays & academic papers), as well as topic dependencies.
- 2013 **Autogrid Systems, Redwood City, CA.**
Software Engineering Intern
Helped build out in-house development and testing infrastructure, transitioned to machine learning, feeding data to generalized machine learning models to predict energy demand spikes.

Teaching Experience

- Autumn 2022 **Head Course Assistant for Stanford CS 221: Introduction to Artificial Intelligence.**
Co-taught by Percy Liang and Dorsa Sadigh; Managing a staff of 14 TAs to design assignments, hold weekly sections, write exams, supervise final projects for an enrollment of 400+ students.
- 2017-2018 **Head Teaching Assistant for Brown CS 1380: Distributed Systems.**
Taught by Theophilus Benson; Managed a staff of 5 TAs to design assignments, grade, and hold additional tutorial sections and office hours. Built new projects on block-chains & cryptocurrencies.
- 2016-2017, **Head Teaching Assistant for Brown CS 2950K/1470: Deep Learning.**
2017-2018 Taught by Eugene Charniak; 2016-2017 was first offering of the class, led a group of 2 other TAs in designing and implementing all projects in Tensorflow 0.4, pulling from topics across NLP, Vision, and Reinforcement Learning. 2017-2018 class grew in size, led a team of 12+ TAs.
- 2016-2017 **Head Teaching Assistant for Brown CS 1460: Computational Linguistics.**
Taught by Eugene Charniak; rewrote assignments in language modeling, machine translation, parsing, topic modeling, and deep learning for representation learning, managing a team of 7 TAs.

Professional Activities

Leadership

- 2020 – 2022 Co-lead of the core development and scaling team for the Center of Research on Foundation Models (CRFM), advised by Percy Liang

Workshop & Symposia Organization

- 2022 Co-organizer for the “**Workshop on Foundation Models for Decision Making (FMDM)**” at *NeurIPS*, with Sherry Yang (UC Berkeley), Yilun Du (MIT), Jack Parker-Holder (DeepMind), Igor Mordatch (Google), Shane Gu (University of Tokyo, Google), and Ofir Nachum (Google).
- 2022 Lead organizer for the “**Workshop on Learning from Diverse, Offline Data (L-DOD)**” at *Robotics: Science and Systems*, with Suraj Nair (Stanford), Dhruv Shah (UC Berkeley), Victoria Dean (CMU), and Professors Percy Liang (Stanford), Chelsea Finn (Stanford), and Dorsa Sadigh (Stanford).
- 2021 Co-organizer for the “**Bay Area Robotics Symposium (BARS)**” with Professors Dorsa Sadigh (Stanford), Mark Mueller (UC Berkeley), and fellow student Erdem Biyik (Stanford).

Journal & Conference Reviewer

- NLP
 - ACL Rolling Review (ARR): October 2021- (Monthly)
 - Association for Computational Linguistics (ACL): 2020-
 - Empirical Methods in Natural Language Processing (EMNLP): 2020-
 - North American Association for Computation Linguistics (NAACL): 2020-

- Robotics
 - Robotics & Automation – Letters (RA-L): 2020-
 - Conference on Robot Learning (CoRL): 2021-
 - International Conference on Robotics & Automation (ICRA): 2020-
 - International Conference on Intelligent Robots & Systems (IROS): 2021-
 - ACM/IEEE Conference on Human-Robot Interaction (HRI): 2022-

- ML
 - Conference on Neural Information Processing Systems (NeurIPS): 2021-
 - International Conference on Learning Representations (ICLR): 2021-
 - International Conference on Machine Learning (ICML): 2021-

Workshop Reviewer

- Robotics & RL
 - Workshop on Foundation Models for Decision Making (FMDM) @ NeurIPS: 2022
 - Workshop on Learning from Diverse, Offline Data (L-DOD) @ RSS: 2022
 - Workshop on Deep Reinforcement Learning @ NeurIPS: 2021-
 - Robot Learning: Self-Supervised & Lifelong Learning @ NeurIPS: 2021-
 - Social Intelligence in Humans and Robotics @ ICRA: 2021-

- NLP
 - Learning with Natural Language Supervision (NL-Sup) @ ACL: 2022
 - Interactive Learning for Natural Language Processing (InterNLP) @ ACL: 2021-
 - Visually Grounded Interaction and Language (ViGiL) @ NAACL: 2021-
 - Novel Ideas in Learning to Learn from Interaction (NILLI) @ EMNLP: 2021
 - Insights from Negative Results in NLP (Insights) @ EMNLP: 2021
 - Spatial Language and Grounding for Robotics (Splu-RoboNLP) @ ACL: 2021

- ML
 - Interactive Machine Learning Workshop (IML) @ AAAI: 2022
 - Controllable Generation (CtrlGen) @ NeurIPS: 2021

University Service

- 2020 – 2022 Editor for the Stanford Artificial Intelligence Blog; responsible for editing student-authored posts and managing the blog website.
- 2019 – 2021 Organized Grounding & Interaction Reading/Research group bringing together students and faculty from NLP, CV, RL, Robotics, and beyond to discuss and present recent work.
- 2020 – 2021 Reviewed Ph.D. applications for Stanford's Computer Science department as part of the Applications Committee.